

ACADEMIC LESSON PLAN OF WINTER 2022

Discipline: ELECTRICAL	Semester: 5 th Sem	Name of the Teaching Faculty: SUDIPTA KUMAR DAS
Subject: ENERGY CONVERSION-II	No. of days/per week class allotted:5p/week	Semester From: 15 ST OCTOBER 2022 to 22 th DECEMBER2022 No. of weeks:13 weeks
Week	Class Day	Theory Topics
1 st	1 ST	1. ALTERNATOR: 1.1. Types of alternator and their constructional features.
	2 ND	1.2. Basic working principle of alternator and the relation between speed and frequency.
2 nd	1 ST	1.3. Terminology in armature winding and expressions for winding factors (Pitch factor, Distribution factor).
3 rd	1 ST	1.4. Explain harmonics, its causes and impact on winding factor.
	2 ND	1.5. E.M.F equation of alternator. (Solve numerical problems).
	3 RD	1.5. E.M.F equation of alternator. (Solve numerical problems).
	4 TH	1.6. Explain Armature reaction and its effect on emf at different power factor of load.
4 th	1 ST	1.7. The vector diagram of loaded alternator. (Solve numerical problems)
	2 ND	1.8. Testing of alternator (Solve numerical problems) 1.8.1. Open circuit test.
		1.8.2. Short circuit test.
	3 RD	
	4 TH	1.9. Determination of voltage regulation of Alternator by direct loading and synchronous impedance method. (Solve numerical problems)
	5 TH	1.9. Determination of voltage regulation of Alternator by direct loading and Synchronous impedance method. (Solve numerical problems)
6 TH	1.10. Parallel operation of alternator using synchro-scope and dark & Brightlamp method.	
5 th	1 ST	1.11. Explain distribution of load by parallel connected alternators.
	2 ND	2. SYNCHRONOUS MOTOR: 2.1. Constructional feature of Synchronous Motor.
		2.2. Principles of operation, concept of load angle
	3 RD	2.3. Derive torque, power developed.
	4 TH	2.4. Effect of varying load with constant excitation. 2.5. Effect of varying excitation with constant load.
5 TH	2.6. Power angle characteristics of cylindrical rotor motor.	
6 th	1 ST	2.7. Explain effect of excitation on Armature current and power factor.
	2 ND	2.8. Hunting in Synchronous Motor. 2.9. Function of Damper Bars in synchronous motor and generator.

	3 RD	2.10. Describe method of starting of Synchronous motor.
	4 TH	2.11. State application of synchronous motor.
7 th	1 ST	3. THREE PHASE INDUCTION MOTOR: 3.1. Production of rotating magnetic field.
	2 ND	3.2. Constructional feature of Squirrel cage and Slip ring induction motors.
	3 RD	3.3. Working principles of operation of 3-phase Induction motor.
	4 TH	3.4. Define fine slip speed, slip and establish the relation of slip with rotor quantities.
	5 TH	3.5. Derive expression for torque during starting and running conditions and derive conditions for maximum torque. (solve numerical problems)
8 th	1 ST	3.6. Torque-slip characteristics.
	2 ND	3.7. Derive relation between full load torque and starting torque etc. (solve numerical problems)
	3 RD	3.8. Establish the relations between Rotor Copper loss, Rotor output and Gross Torque and relationship of slip with rotor copper loss. (solve numerical problems)
	4 TH	3.9. Methods of starting and different types of starters used for three phase Induction motor.
	5 TH	3.10. Explain speed control by Voltage Control, Rotor resistance control, Pole changing, frequency control methods.
9 th	1 ST	3.10. Explain speed control by Voltage Control, Rotor resistance control, Pole changing, frequency control methods.
	2 ND	3.11. Plugging as applicable to three phase induction motor.
	3 RD	3.12. Describe different types of motor enclosures.
	4 TH	3.13. Explain principle of Induction Generator and state its applications.
	5 TH	4. SINGLE PHASE INDUCTION MOTOR: 4.1. Introduction and Explain Ferrari's principle.
	5 TH	4.2. Explain double revolving field theory and Cross-field theory to analyze starting torque of 1-phase induction motor.
10 th	1 ST	4.2. Explain double revolving field theory and Cross-field theory to analyze starting torque of 1-phase induction motor.
	2 ND	4.3. Explain Working principle, Torque speed characteristics, performance characteristics and application of following single phase motors. 4.3.1. Split phase motor.
	3 RD	4.3.2. Capacitor Start motor. 4.3.3. Capacitor start, capacitor run motor.
	4 TH	4.3.4. Permanent capacitor type motor. 4.3.5. Shaded pole motor.

	5 TH	4.4. Explain the method to change the direction of rotation of above motors.
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	5 TH	5. COMMUTATOR MOTORS: 5.1. Construction, working principle, running characteristic and application of single phase series motor.
11 th	1 ST	5.1. Construction, working principle, running characteristic and application of single phase series motor.
	2 ND	5.2. Construction, working principle and application of Universal motors.
	3 RD	5.2. Construction, working principle and application of Universal motors.
	4 TH	5.3. Working principle of Repulsion start Motor, Repulsion start Induction run motor, Repulsion Induction motor.
	5 TH	5.3. Working principle of Repulsion start Motor, Repulsion start Induction run motor, Repulsion Induction motor.
12 th	1 ST	6. SPECIAL ELECTRICAL MACHINE: 6.1. Principle of Stepper motor. 6.2. Classification of Stepper motor.
	2 ND	6.3. Principle of variable reluctant stepper motor.
	3 RD	6.4. Principle of Permanent magnet stepper motor.
	4 TH	6.5. Principle of hybrid stepper motor.
	5 TH	6.6. Applications of Stepper motor.
13 th	1 ST	7. THREE PHASE TRANSFORMERS: 7.1. Explain Grouping of winding, Advantages.
	2 ND	7.2. Explain parallel operation of the three phase transformers.
	3 RD	7.2. Explain parallel operation of the three phase transformers.
	4 TH	7.3. Explain tap changer (On/Off load tap changing)
	5 TH	7.4. Maintenance Schedule of Power Transformers

